

Neuroscience out of control

Control-theoretic methods
for understanding neural circuits

Guillaume Hennequin

g.hennequin@eng.cam.ac.uk

Lisbon, March 2019

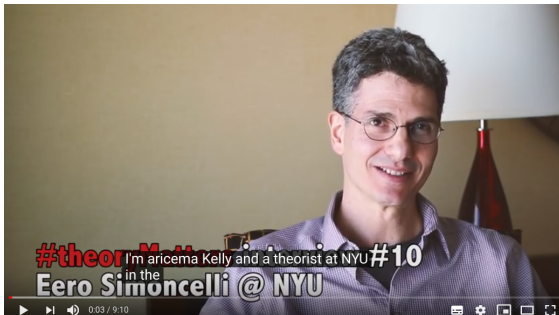


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CAMBRIDGE





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matrices ——— ? ———> dynamical system

A, B, C

$$\dot{\mathbf{x}} = \mathbf{A}\mathbf{x}(t) + \mathbf{B}\mathbf{u}(t)$$

$$\mathbf{y} = \mathbf{C}\mathbf{x}$$



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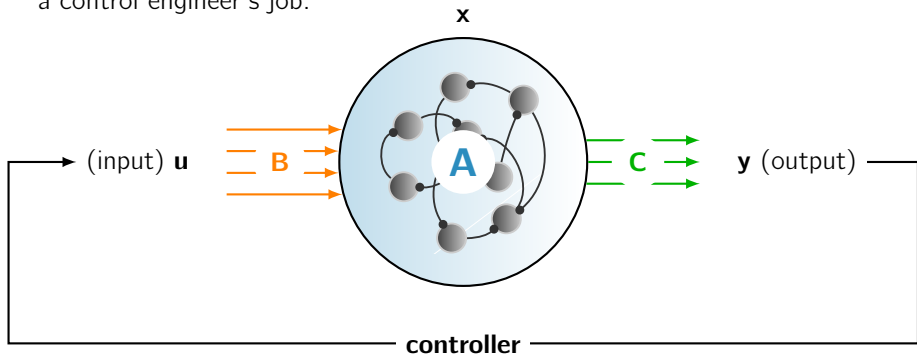
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many decades of insights from control theory, too rarely used in neuro 😞

a control engineer's job:



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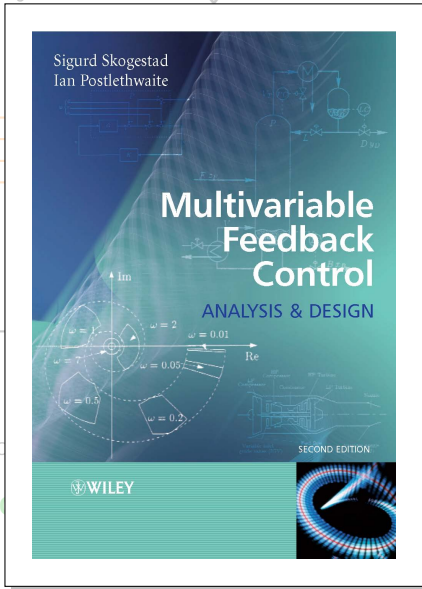
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many decades of insights from control theory, too rarely used in neuro 🙄

a control engineer's job:



matrix

A, B, C

system

$Bu(t)$

$= Cx$

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Linear systems in neuroscience

$$\tau \frac{d\mathbf{x}}{dt} = -\mathbf{x} + \mathbf{W}\mathbf{x} + \text{external input}$$

population firing rate vector, or latent variables

connectivity matrix

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short-term memory

VOLUME 92, NUMBER 14

PHYSICAL REVIEW LETTERS

week ending
9 APRIL 2004

Short-Term Memory in Orthogonal Neural Networks

Olivia L. White,¹ Daniel D. Lee,² and Haim Sompolinsky^{1,3}

¹Harvard University, Cambridge, Massachusetts 02138, USA

²University of Pennsylvania, Philadelphia, Pennsylvania 19104, USA

³Racah Institute of Physics and Center for Neural Computation, Hebrew University, Jerusalem 91904, Israel
(Received 11 November 2003; published 9 April 2004)

We study the ability of linear recurrent networks obeying discrete time dynamics to store long temporal sequences that are retrievable from the instantaneous state of the network. We calculate this temporal memory capacity for both distributed shift register and random orthogonal connectivity matrices. We show that the memory capacity of these networks scales with system size.

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temporal
matrices.



Memory traces in dynamical systems

Surya Gangulija^{a,b,1}, Dongsung Huh^c, and Haim Sompolinsky^{d,e}

^aSloan-Swartz Center for Theoretical Neurobiology, University of California, San Francisco, CA 94143; ^bCenter for Neural Computation, The Hebrew University, Jerusalem 91904, Israel; and ^cCenter for Brain Science, Har

Communicated by David W. McLaughlin, New York University, New York, NY, October 3, 2008 (received for

To perform nontrivial, real-time computations on a sensory input stream, biological systems must retain a short-term memory trace these questions in a m
mation to construct a n

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Previews

Feedforward to the Past: The Relation between Neuronal Connectivity, Amplification, and Short-Term Memory

Surya Ganguli^{1,*} and Peter Latham²

¹Sloan-Swartz Center for Theoretical Neurobiology, University of California, San Francisco, San Francisco, CA 94143, USA

²Gatsby Computational Neuroscience Unit, UCL, London WC1N 3AR, UK

*Correspondence: surya@phy.ucsf.edu

DOI 10.1016/j.neuron.2009.02.006

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DOI 10.1016/j.neuro

Neuron

Article

Memory without Feedback in a Neural Network

Mark S. Goldman^{1,*}

¹Center for Neuroscience, Section of Neurobiology, Physiology, and Behavior, and Department of Ophthalmology and Visu
University of California, Davis, Davis, CA 95618, USA

*Correspondence: msgoldman@ucdavis.edu
DOI 10.1016/j.neuron.2008.12.012

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decision-making

Neuron

Viewpoint

One-Dimensional Dynamics of Attention and Decision Making in LIP

Surya Ganguli,^{1,7,*} James W. Bisley,² Jamie D. Roitman,³ Michael N. Shadlen,⁴ Michael E. Goldberg,^{5,6} and Kenneth D. Miller^{5,7}

¹Sloan-Swartz Center for Theoretical Neurobiology, University of California, San Francisco, San Francisco, CA 94143, USA

²Department of Neurobiology, University of California, Los Angeles, Los Angeles, CA 90025, USA

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V1

Balanced Amplification: A New Mechanism of Selective Amplification of Neural Activity Patterns

Brendan K. Murphy^{1,2}

¹Graduate Group in Biophysics

²Center for Theoretical Neuroscience

College of Physicians and Surgeons

*Correspondence: ken@neurotheory.columbia.edu

DOI 10.1016/j.neuron.2009.03.028

Inhibitory Stabilization of the Cortical Network Underlies Visual Surround Suppression

Hirofumi Ozeki,¹ Ian M. Finn,¹ Evan S. Schaffer,² Kenneth D. Miller,^{2,3,*} and David Ferster^{1,3,*}

¹Department of Neurobiology and Physiology, Northwestern University, Evanston, IL 60208, USA

²Center for Theoretical Neuroscience and Department of Neuroscience, Columbia University, College of Physicians and Surgeons, New York, NY 10032, USA

³These authors contributed equally to this work

*Correspondence: ken@neurotheory.columbia.edu (K.D.M.), ferster@northwestern.edu (D.F.)

DOI 10.1016/j.neuron.2009.03.028

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Optimal Control of Transient Dynamics in Balanced Networks Supports Generation of Complex Movements

Guillaume Hennequin,^{1,2,*} Tim P. Vogels,^{1,3,4} and Wulfram Gerstner^{1,4}

¹School of Computer and
Lausanne (EPFL), 1015 La

²Department of Engineering

³Centre for Neural Circuits

⁴Co-senior author

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<http://dx.doi.org/10.1016/j.neuron.2015.05.030>

A neural network that finds a naturalistic solution for the production of muscle activity

David Sussillo¹, Mark M Churchland², Matthew T Kaufman^{1,4} & Krishna V Shenoy^{1,3}

It remains an open question how neural responses in motor cortex relate to movement. We explored the hypothesis that motor cortex reflects dynamics appropriate for generating temporally patterned outgoing commands. To formalize this hypothesis, we trained recurrent neural networks to reproduce the muscle activity of reaching monkeys. Models had to infer dynamics that co-transform simple inputs into temporally and spatially complex patterns of muscle activity. Analysis of trained models revealed that the natural dynamical solution was a low-dimensional oscillator that generated the necessary multiphasic commands.

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correlations

PHYSICAL REVIEW E

VOLUME 50, NUMBER 4

OCTOBER 1994

Theory of correlations in stochastic neural networks

School of

[OPEN ACCESS](#) Freely available online

PLOS COMPUTATIONAL BIOLOGY

Racah

How Structure Determines Correlations in Neuronal Networks

Volker Pernice^{1,2*},

¹Bernstein Center Freiburg, F

Insights from a Simple Expression for Linear Fisher Information in a Recurrently Connected Population of Spiking Neurons

Jeffrey Beck
jbeck@bcs.roche

Gatsby Comput
London, WC1N

The Dynamical Regime of Sensory Cortex: Stable Dynamics around a Single Stimulus-Tuned Attractor Account for Patterns of Noise Variability

Guillaume Hennequin,^{1,10,*} Yashar Ahmadian,^{2,3,4,5,9} Daniel B. Rubin,^{2,6,9} Máté Lengyel,^{1,7,8} and Kenneth D. Miller^{2,3,8}

¹Computational and Biological Learning Lab, Department of Engineering, University of Cambridge, Cambridge CB2 1PZ, UK

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correlations

deep learning (!)

Exact solutions to the nonlinear dynamics of learning in deep linear neural networks

Andrew M
Depart

James L. McClelland

Surya Ganguli
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Stanford U

High-dimensional dynamics of generalization error in neural networks

Madhu S. Advani*
Center for Brain Science
Harvard University
Cambridge, MA 02138

MADVANI@FAS.HARVARD.EDU

Andrew M. Saxe*
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Exact s

Exact natural gradient in deep linear networks and application to the nonlinear case

Alberto Bernacchia
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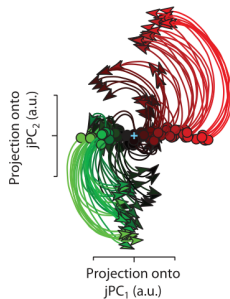
data analysis / system identification

ARTICLE

doi:10.1038/nature11129

Neural population dynamics during reaching

Mark M. Churchland^{1,2,3*}, John P. Cunningham^{4,5*}, Matthew T. Kaufman^{2,3}, Justin D. Foster², Paul Nuyujukian^{6,7}, Stephen I. Ryu^{2,8} & Krishna V. Shenoy^{2,3,6,9}



Linear systems in neuroscience

Latent variable modeling is all about constraints

Observation Model (data type, function class, noise model)

Dynamics Model (type, function class, noise model)	Continuous Linear Gaussian	Discrete (Gen.) Linear Recurrent/Sequential/etc.	Nonlinear Observation Models	
	Discrete Markovian Categorical	HMM Rabiner (1989)	HMM Rabiner (1989)	Structured VAE Johnson et al (2016)
	Continuous Linear Gaussian	LDS Kulkarni (1992)	Poisson LDS Smith and Brown (2003), Parizodi et al (2010), Macke et al (2011)	Deep PFLDS Archer et al (2015); Gao et al (2016)
	Continuous Nonlinear (parametric) Gaussian	NLDS, e.g. Hodgkin-Huxley Alves, Hunt, Parizi (2009), Wang and Ripstein (2009)	NLDS, e.g. Hodgkin-Huxley Mang, Komar, Eden (2013)	GPSSM, DKF, LFAFS, VIND Frigola et al (2013), Krishnan et al (2015), Sussillo et al (2016), Hernandez et al (2018)
	Mixed Switching Linear	SLDS Ghahramani and Hinton (1996), Murphy (1998)	Poisson SLDS Petreska et al (2013)	Structured VAE Johnson et al (2016)
	Mixed Recurrent Linear	recurrent/augmented SLDS Barber (2004), Parizodi et al (2010), Linderman et al (2017), Foster et al (2019)	rSLDS Linderman et al (2017), Foster et al (2019)	Structured VAE Johnson et al (2016)
	Continuous Nonlinear (nonparametric) Gaussian	GPFA Yu, Cunningham, et al (2009)	vLGP Zhao and Park (2017)	GPLVM Lawrence (2005), Wu et al (2017)
	Continuous Nonlinear (nonparametric) Gaussian	GPSSM, DKF, LFAFS, VIND Frigola et al (2013), Krishnan et al (2015), Sussillo et al (2016), Hernandez et al (2018)	GPSSM, DKF, LFAFS, VIND Frigola et al (2013), Krishnan et al (2015), Sussillo et al (2016), Hernandez et al (2018)	GPSSM, DKF, LFAFS, VIND Frigola et al (2013), Krishnan et al (2015), Sussillo et al (2016), Hernandez et al (2018)

[Scott Linderman, this morning]

Analysis of linear dynamics

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↖ population firing rate vector, or latent variables
↓
connectivity matrix

- ▶ (dynamics analytically solvable)

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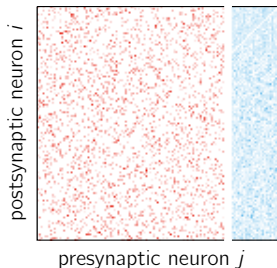
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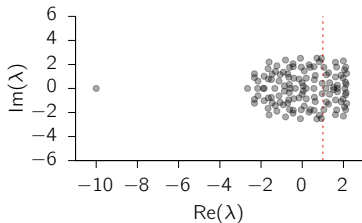
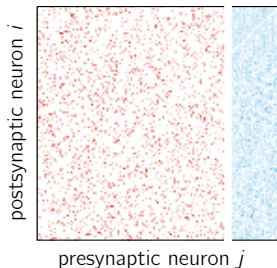
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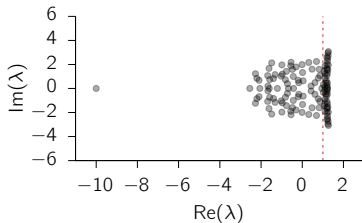
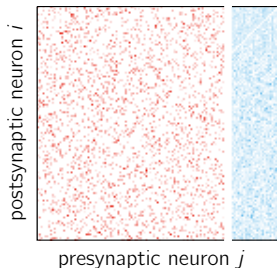
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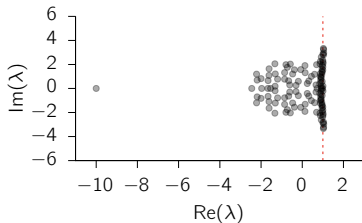
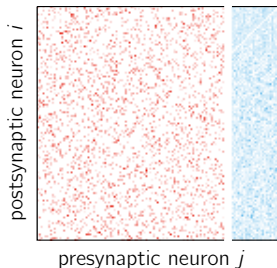
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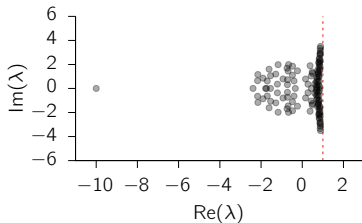
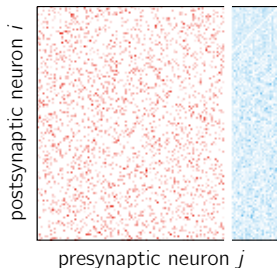
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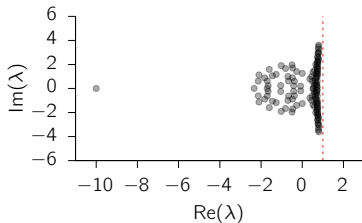
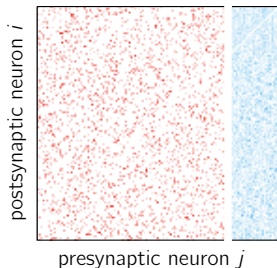
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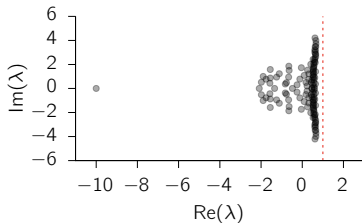
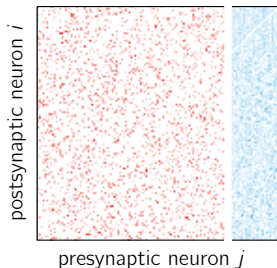
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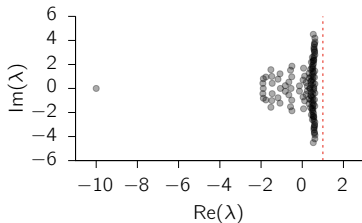
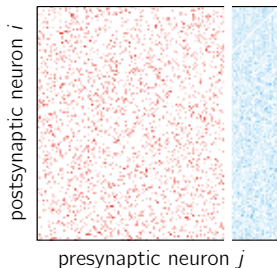
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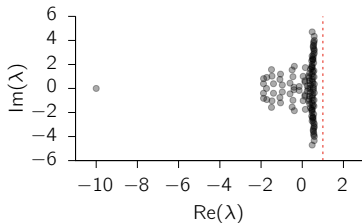
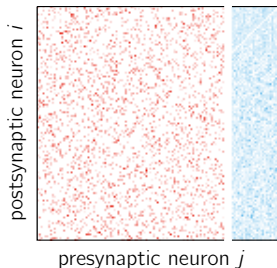
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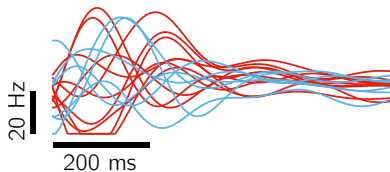
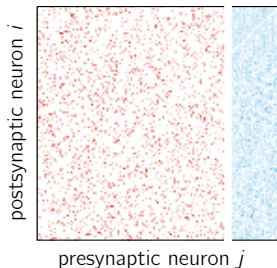
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Analysis of linear dynamics

$$\mathbf{T} \frac{d\mathbf{x}}{dt} = -\mathbf{x} + \mathbf{W}\mathbf{x} + \text{external input}$$

↖ population firing rate vector, or latent variables
↓
connectivity matrix

- ▶ (dynamics analytically solvable)
- ▶ eigendecomposition – probably only useful for “normal” architectures [Carandini & Ringach '97; Dayan & Abbott '01; Ganguli et al. '08]
- ▶ Schur decomposition – useful description of “nonnormal” architectures, but non-unique [Murphy & Miller, '09, Goldman '09, Hennequin et al. '12]



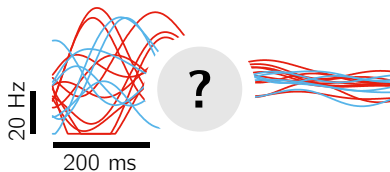
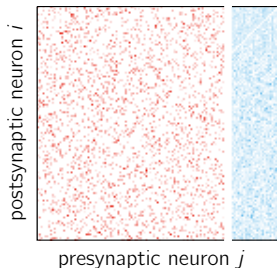
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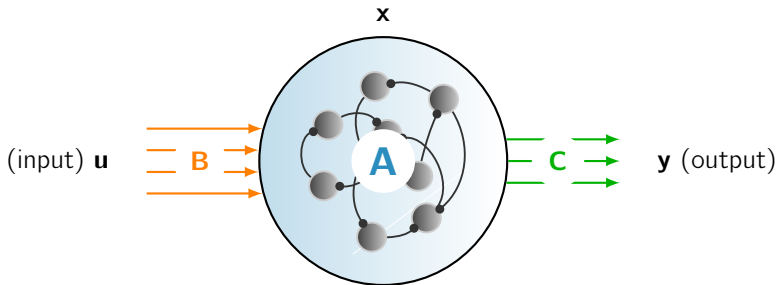
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Controllability & Observability

(two-sided “extension of PCA” to *dynamical systems*)

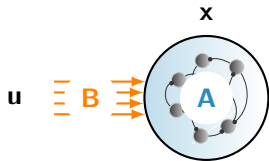


$$\dot{x} = Ax(t) + Bu(t)$$

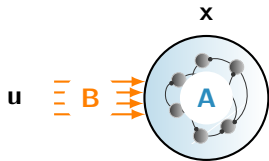
$$y = Cx$$

controllability & observability are core concepts in control-theory that afford useful re-interpretations for the analysis of circuits

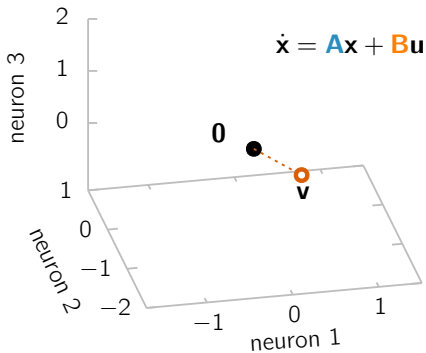
Controllability & Observability



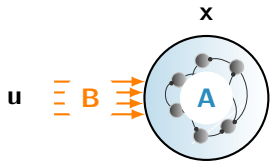
Controllability & Observability



using these input channels,
can I steer \mathbf{x} from $\mathbf{0}$ to any \mathbf{v} ?



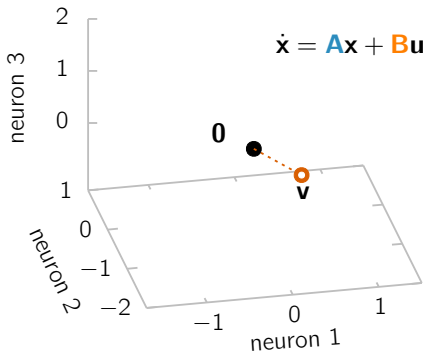
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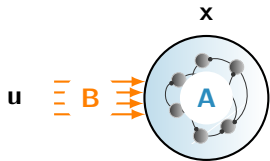
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controllability Gramian $\mathbf{P} \succeq 0$

$$\mathbf{P} \equiv \int_0^{\infty} \exp(t\mathbf{A})\mathbf{B}\mathbf{B}^T \exp(t\mathbf{A}^T) dt$$



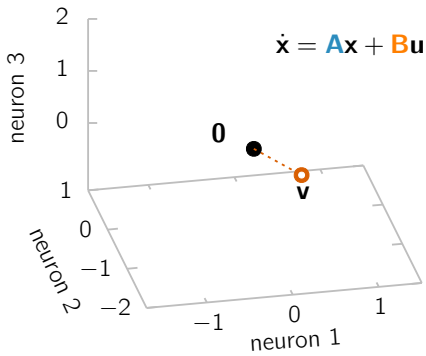
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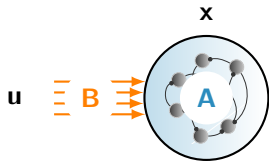
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Controllability & Observability



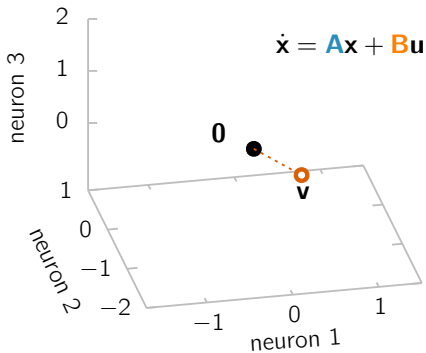
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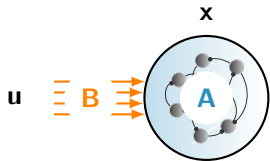
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how much input energy is required



Controllability & Observability



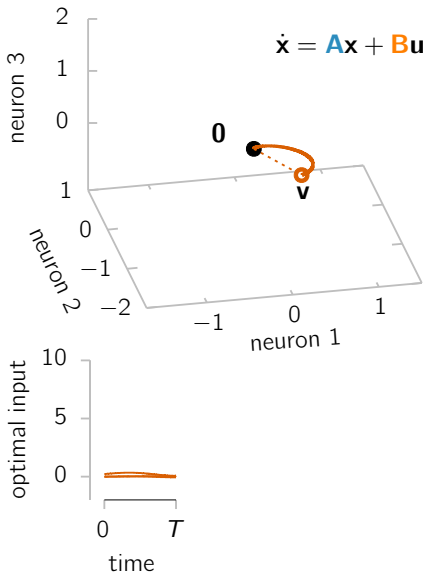
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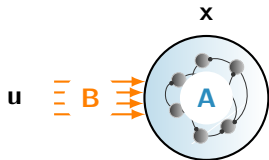
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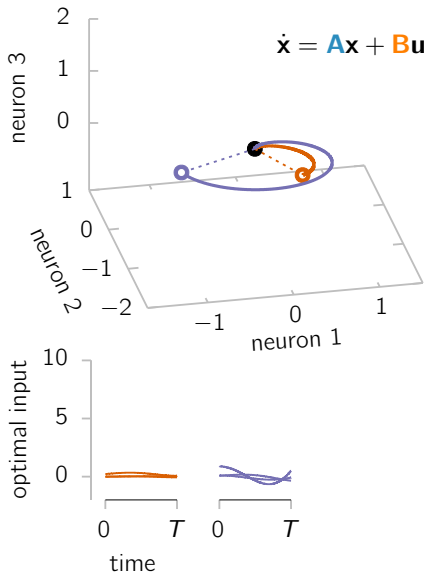
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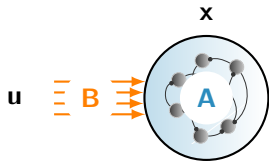
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Controllability & Observability



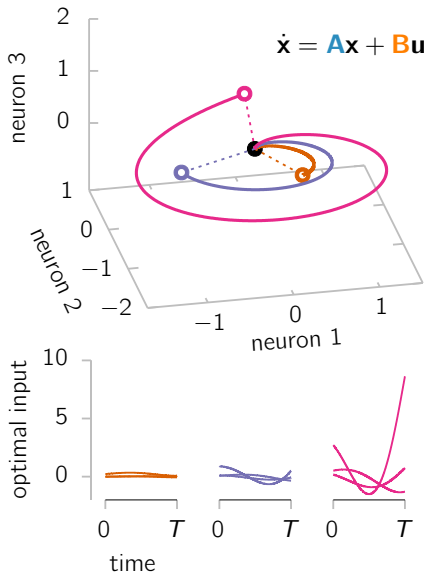
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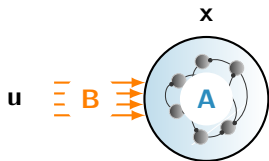
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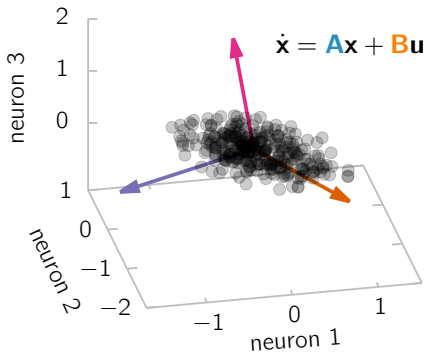
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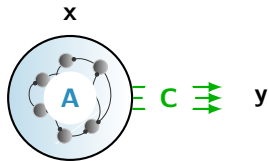


if $\mathbf{u}(t) =$ white noise

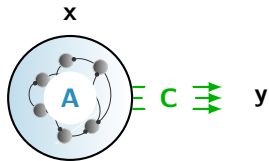
$$\mathbf{P} = \langle \mathbf{x}(t)\mathbf{x}(t)^T \rangle_t$$

cf. "intrinsic manifold"
[Sadler et al., *Nature* (2010)]

Controllability & Observability

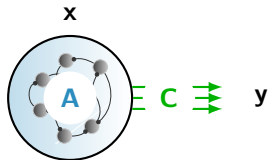


Controllability & Observability



if I observe $\mathbf{u}(t)$ and $\mathbf{y}(t)$,
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Controllability & Observability

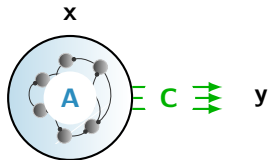


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Controllability & Observability

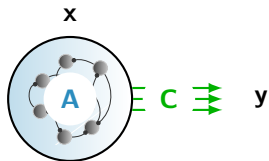


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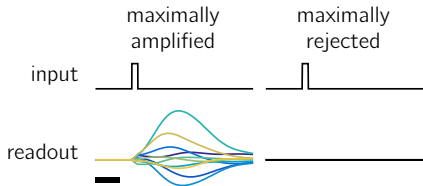
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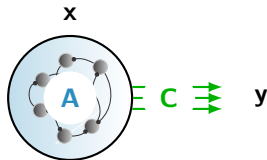
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alternative, useful interpretation:

$\mathbf{x}_0^T \mathbf{Q} \mathbf{x}_0$ is the output energy evoked by initial condition \mathbf{x}_0



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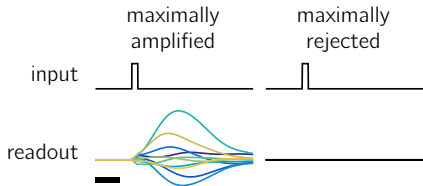
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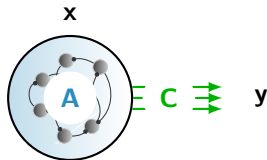
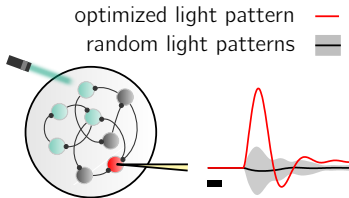
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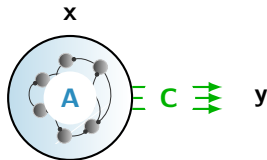
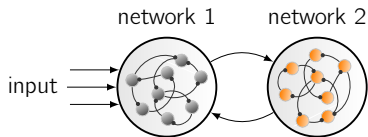
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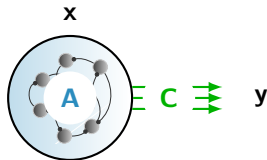
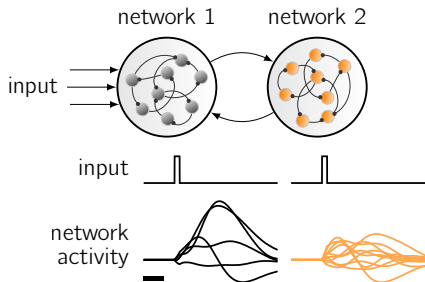
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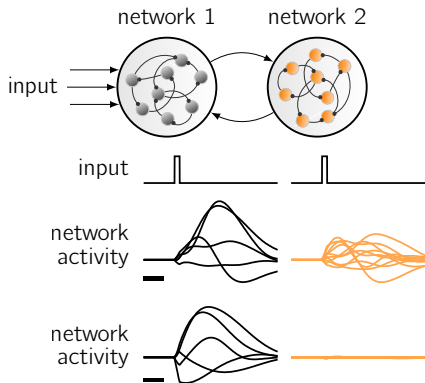
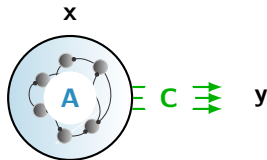
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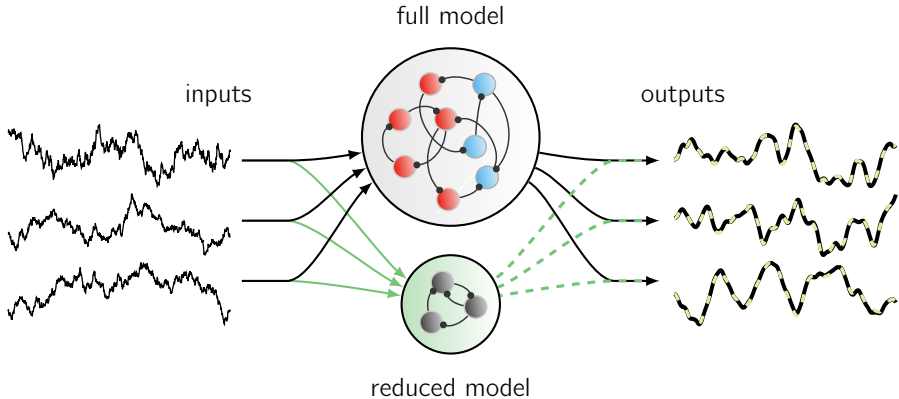
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“dynamical nullspace” [Duncker et al., Cosyne '17]

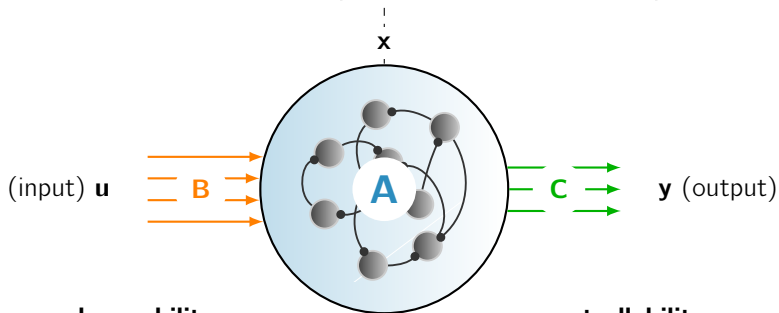
Model reduction



classic methods try to capture the top subspace of both \mathbf{P} and \mathbf{Q}

fun fact: for our ISN model of M1, we recover rotational dynamics
(also revealed by jPCA)

Observability & Controllability



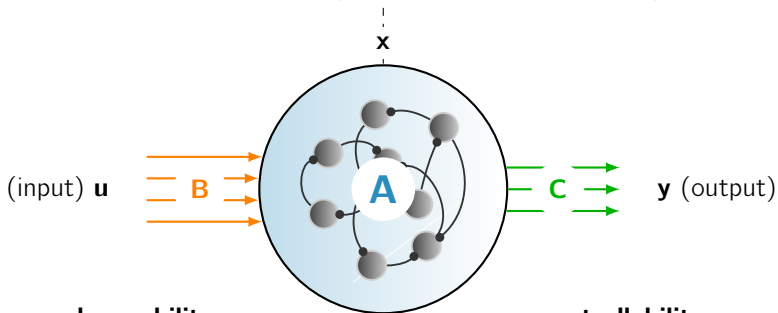
observability:

“what input patterns is my network most/least sensitive to?”

controllability:

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Observability & Controllability



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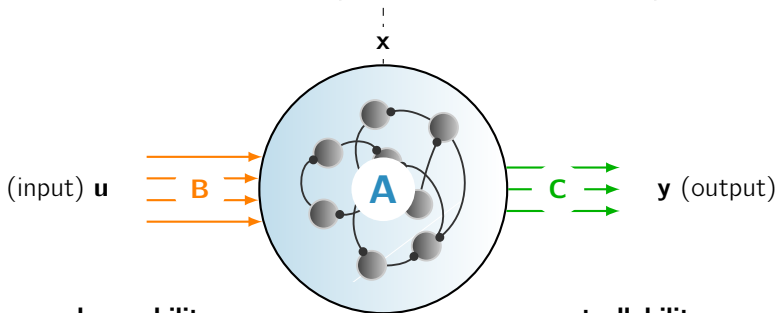
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P and **Q** are all you need to know about **A**

for biologically realistic (nonnormal) networks, **P** \neq **Q**

[Kao, Sadabadi & Hennequin, Cosyne '18]

Observability & Controllability



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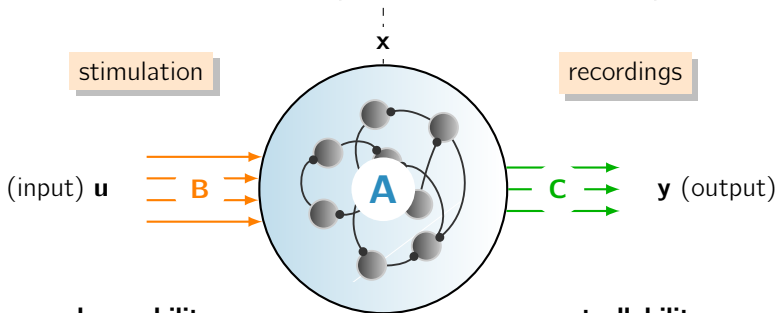
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System identification



Calvin Kao

simplified scenario ($N = 5$):

$$\mathbf{x}_{t+1} = \mathbf{A}\mathbf{x}_t + \text{noise}$$

$$\mathbf{y}_t = \mathbf{x}_t + \text{noise}$$

maximum likelihood parameter estimation
(new method, regularised, stable)

$$\hat{\mathbf{A}} = \operatorname{argmax}_{\mathbf{A}} \log p(\mathbf{y}_{0:T} | \mathbf{A})$$

System identification



Calvin Kao

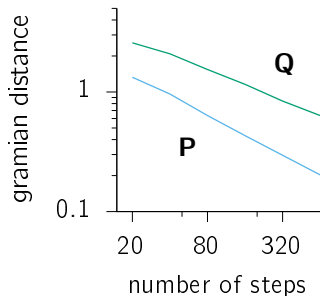
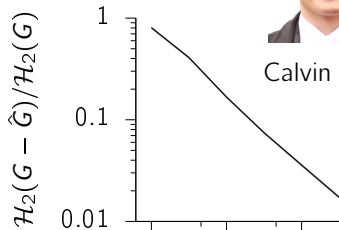
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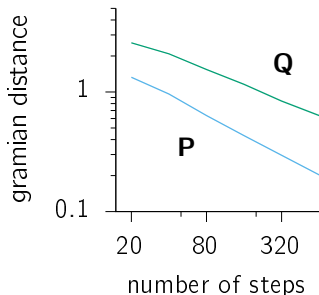
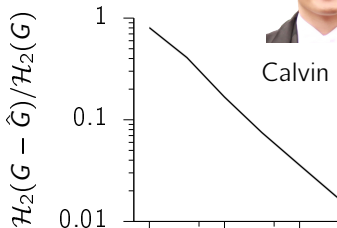
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Q recovered less accurately than **P**

learned model not very predictive of
the effect of stimulation



Outlook

control-theoretic perspectives on RNNs offers new ways of understanding them (here, we've barely scratched the surface)

use of optogenetic access to constrain **I/O models** of neural circuits

motor control, BCIs, reinforcement learning, behavioural modelling, . . .